

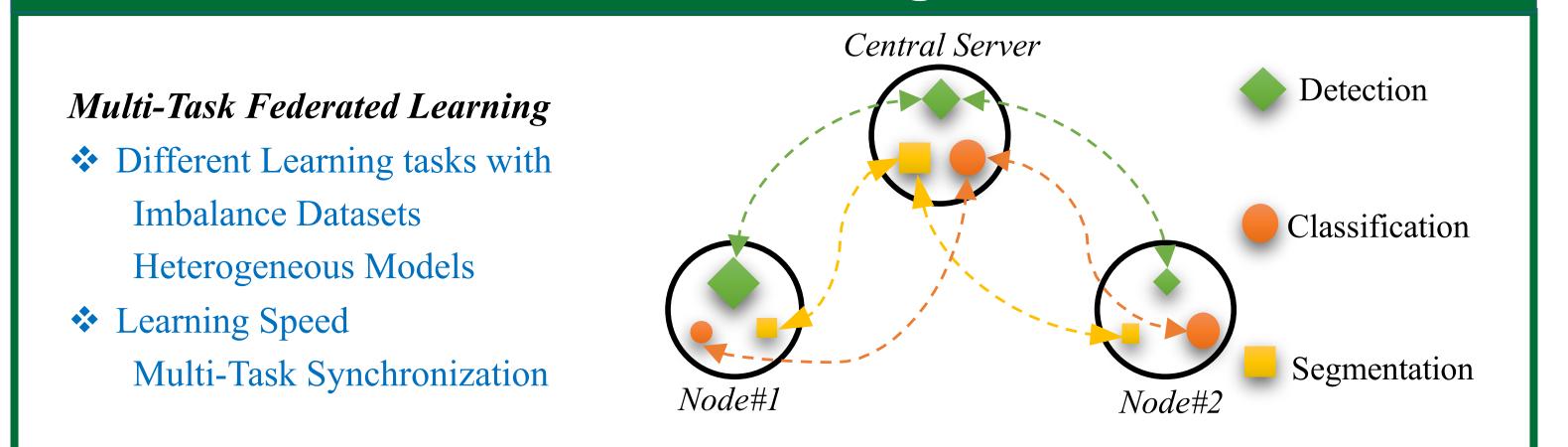
# **Powering Multi-Task Federated Learning with Competitive GPU Resource Sharing**

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# **1.** Multi-Task Federated Learning

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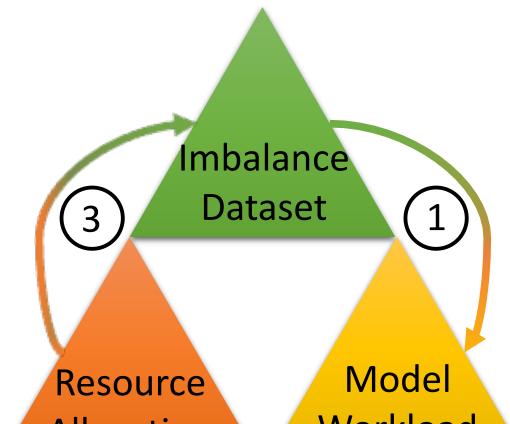
# 3. Inter-device Multi-Task FL coordination

#### **Coordination Design Motivation:** We rethink the FL coordination from a GPU scheduling perspective under imbalance dataset,

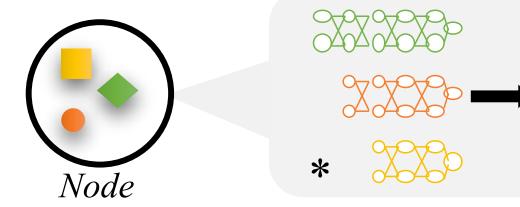
model workload and resource allocation.

#### **Our Objectives:**

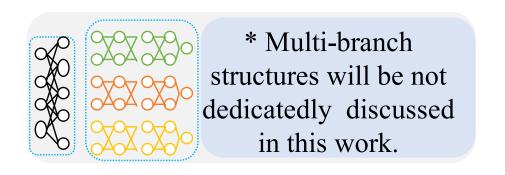
(1) Each device could be fully utilized during each synchronization cycle;



#### Multi-Task Deployment with Parallel Model Structures



Imbalance Training Dataset and Heterogeneous Model Structure bring different training workload and result in different training speeds.



- New Challenges for Computing and Coordination
- Multi-Task Parallel Computing Deployment
- Different Learning Speed Multi-Task Coordination

#### We propose a full-stack multi-task FL optimization scheme:

- intra-device GPU scheduling with a competitive resource sharing scheme;
- inter- device FL coordination with realistic GPU runtime synchronization.

# 2. Intra-Device Multi-Task Resource Allocation

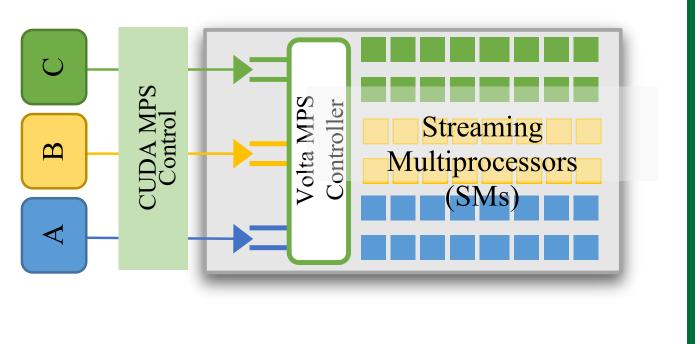
#### Multi-Task Parallel Deployment Mechanism

How to achieve effective multi-task dedicated

GPU resource allocation.

#### **Challenges:**

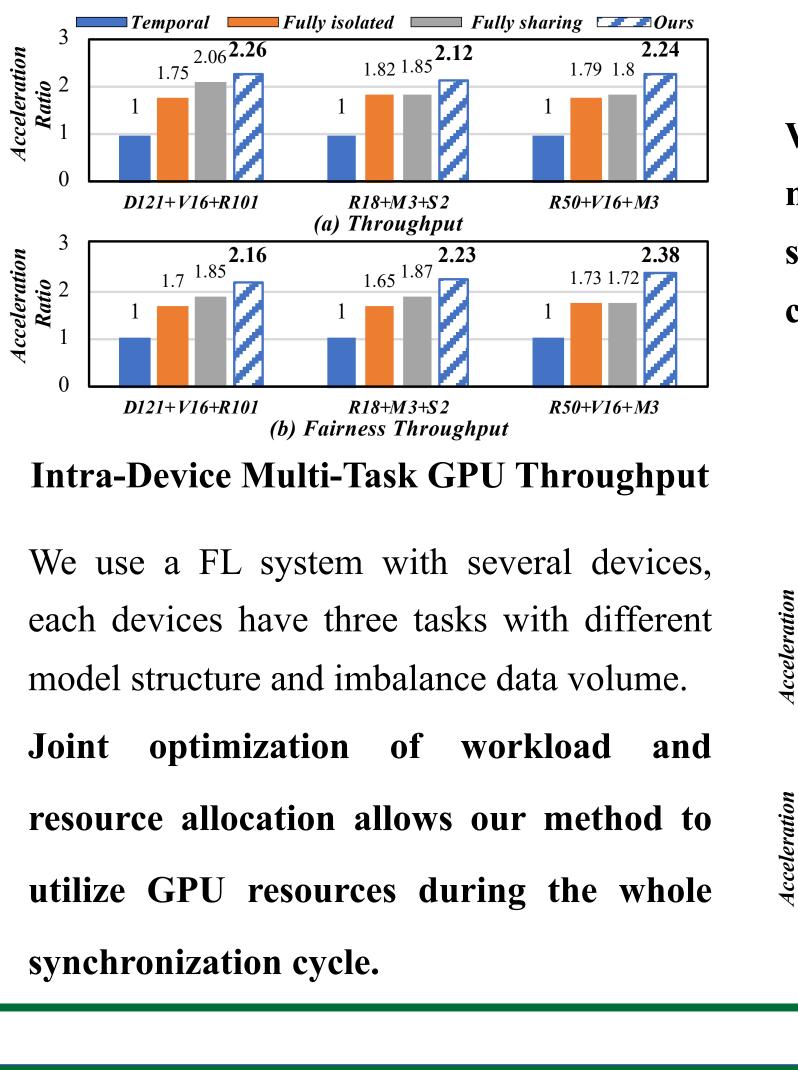
- Identify the parallel computing issue;
- Establish the relationship between



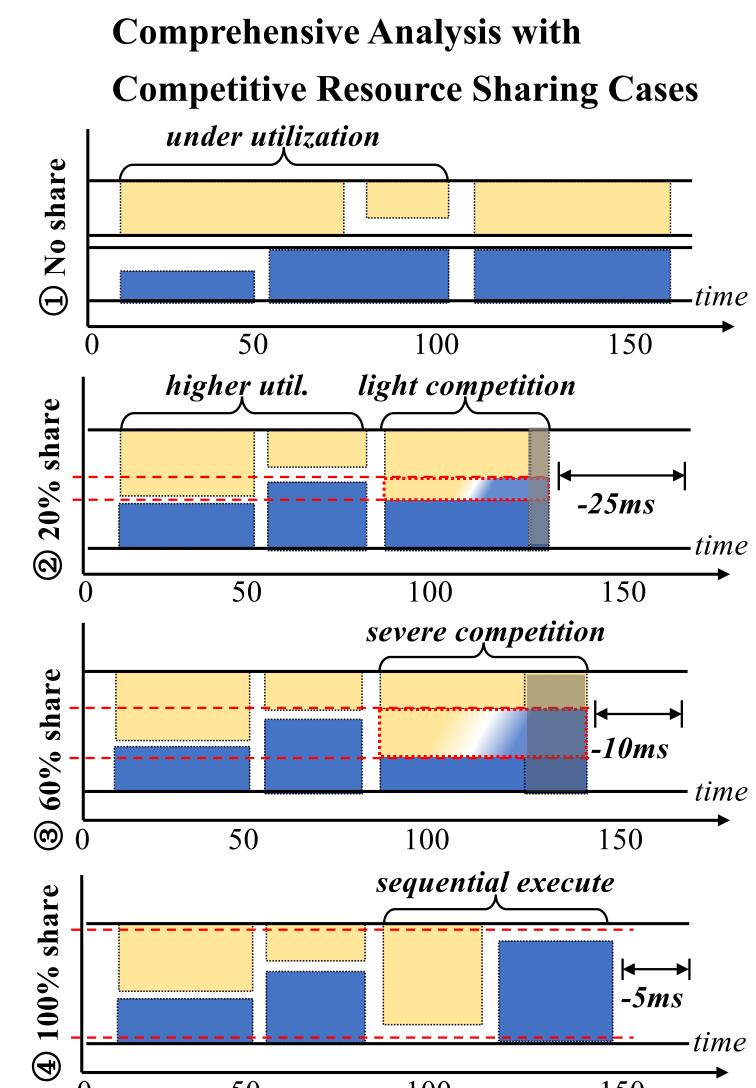
Workload Allocation (2) Maximize the overall GPU throughput P.  $\begin{cases} \text{LocalTraining} : \min_{\{W_{0,j}\}_{j=0}^{J}} Loss(D_{0,j}, W_{0,j}), \\ Fusing: W_{i,j}^{\{k^{th}cycle\}} = \sum_{j=0}^{J} \frac{|D_{0,j}|}{\sum_{k=0}^{J} |D_{0,k}|} W_{i,j}^{\{k-1^{th}cycle\}}. \end{cases}$ Multi-Task Federated Learning with J devices in a federation cluster, each device has *I* tasks  $\int Objective \ 1: \min \sum_{i} \sum_{j} \frac{|D_i|}{|D_j|} - \frac{O_i}{O_j}, \quad \text{Tri-party Optimization to Achieve Objection} \\ 1. \ Larger \ Dataset \ Dneed \ larger \ Workload \ O;$ **Tri-party Optimization to Achieve Objective 1:** Objective 2: max  $\sum_{i} P_1, \dots, P_i$ . 2. Larger Workloads O compete for more Resources; 3. More Resources train more data each cycle.

We use greed optimization method to find the optimal batch size and resource allocation.

## 4. Experimental Results



performance and resource allocation.





**Isolated Spatial Resource Allocation** Exclusive resource assignment causes under-utilization.

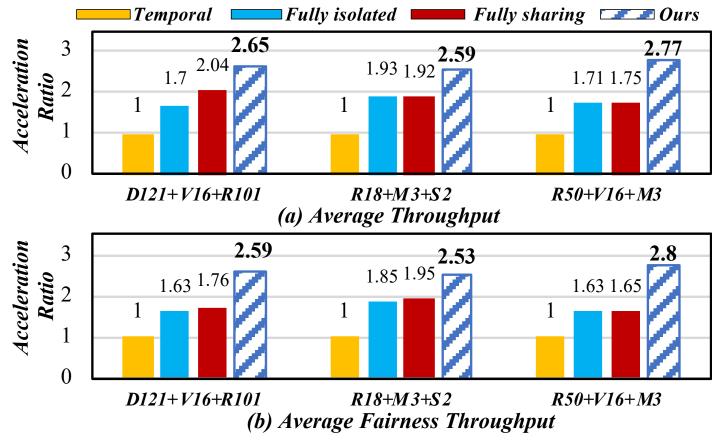
**Spatial Sharing with Light Competition** Higher resource allocation flexibility and better resource utilization.

#### **Sharing with Excessive Competition** Leading to resource competition and considerable contention overhead.

### **Extreme Contention Kills Parallelism** Push back to temporal scheduling when fully sharing the resource without partitioning.

We can apply our resources allocation method on various multi-task training scenarios under multiple DNN models' combinations.

#### **Inter-Device Average Throughput in a Federated Learning Synchronization Cycle**



### 5. Contribution and Conclusion

We analyze the competitive resource sharing mechanism propose an intra-device multi-task dedicated GPU scheduling method.

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#### **Optimization Insights!**

Controlling an appropriate degree of resource competition and sharing is the key to achieve the optimal performance.

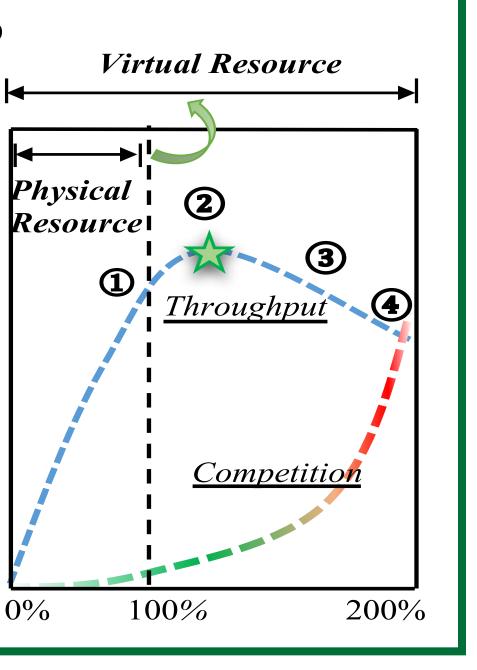
"Virtual Resource" management to establish the relationship between performance and resource allocation.

**Definition of Virtual Resource** :

Virtual resource is a number between  $(0\% \sim 100\%) \times (I \text{ of tasks})$ .

As shown in the right figure, the four points correspond to the above four cases.

We propose a machine learning approach to estimate the GPU throughput *P* and achieve the maximum throughput.



• We further bring competitive resource sharing mechanism into the inter-device FL cluster and rethink the FL coordination from a GPU scheduling perspective. Beyond some FL methods which resolve the heterogeneous problems from algorithmic level, FL's heterogeneous research should also dive into computation level due to imbalance dataset, heterogeneous model and different learning speed per task.

### 6. Reference

[1] Shinpei Kato et al. TimeGraph: GPU scheduling for real-time multi-tasking environments. In Proceedings of the USENIX ATC. 17–30. [2] TianLietal.2020. Federated learning: Challenges, methods, and future directions. IEEE Signal Processing Magazine 3 (2020), 50–60. [3] Nvidia. MPS. https://docs.nvidia.com/deploy/pdf/CUDA\_Multi\_Process\_Service\_Overview.pdf

[4]. Mehdi Salehi Heydar Abad et al. Hierarchical federated learning across heterogeneous cellular networks. In Proceedings of the ICASSP IEEE International Conference on Acoustics, Speech and Signal Processing. IEEE, 8866–8870.