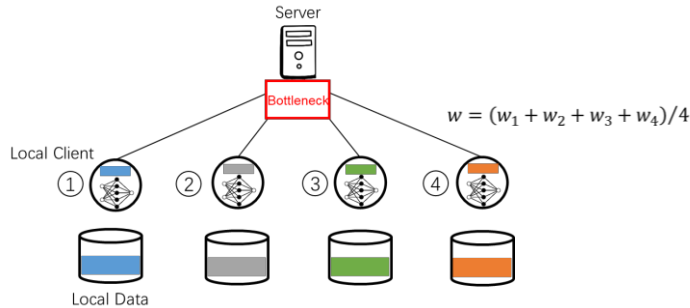


DYNAMIC DECENTRALIZED FEDERATED LEARNING

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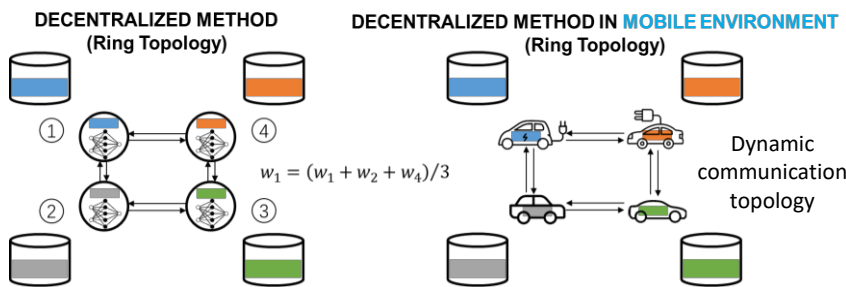
FEDERATED LEARNING & ITS LIMITATIONS

- Federated Learning (FL) trains a shared model through training decentralized data over clients while communicating only model updates
- The server may become a bottleneck as the number of clients increases



DYNAMIC DECENTRALIZED FL

- Decentralized FL: clients share their model updates with their neighbors instead of the central coordinator



PROPOSED ALGORITHM

- Dynamic decentralized FL on the i th client
- Input:** initial point $w_{0,i}$, communication matrix E , the number of iterations K
 - for** $k = 0, \dots, K - 1$ **do**

Random sample data; Update the local model using the sampled data;
Average the local model with neighbors: $w_{k+1,i} = \sum_{j=1}^n E_{ij} w_{k,j}$

MLWiNS: Distributed Learning for the Nomadic Edge (CNS-2003129); PI: Suman Banerjee

- where every entry E_{ij} of the communication matrix $E \in \mathbb{R}^{n \times n}$ shows how much will client j have impact on client i

$$E_{ij} = \begin{cases} 1/n & \text{if } j \neq i \text{ and } j \text{ is a neighbor of } i, \\ 1 - |\text{neighbor of } i|/n & \text{if } j = i, \\ 0 & \text{otherwise.} \end{cases}$$

CONVERGENCE RATE ANALYSIS

- We consider solving the following optimization problem

$$\min_{w \in \mathbb{R}^N} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

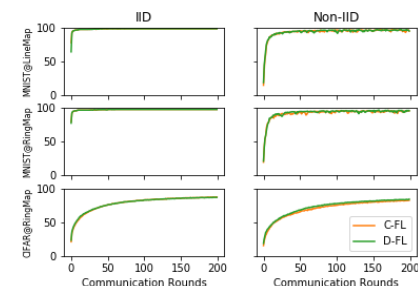
where each $f_i: \mathbb{R}^N \rightarrow \mathbb{R}$ is the local objective function of client i

- Assumptions: Lipschitz gradient & Spectral gap & Bounded variance & Start from 0 & the clients are connected sufficiently often in time
- Theorem: the convergence rate for dynamic decentralized FL is $O\left(\frac{1}{K} + \frac{1}{\sqrt{nK}}\right)$

if the number of iterations K is large enough

EXPERIMENTAL RESULTS

Test Accuracy in various settings. Results validate our theory since D-FL has the same convergence rate.



FUTURE WORK

- Generate a dataset from virtual agents in a virtual world
- Compared with the pre-existing FL datasets, this dataset is
 - more conform to the actual data collected from mobile nodes
 - naturally partitioned
 - having a realistic modeling for the dynamic graph

References

Lian et al. (2017). Can decentralized algorithms outperform centralized algorithms?
Nedic et al. (2008). Distributed subgradient methods and quantization effects.